

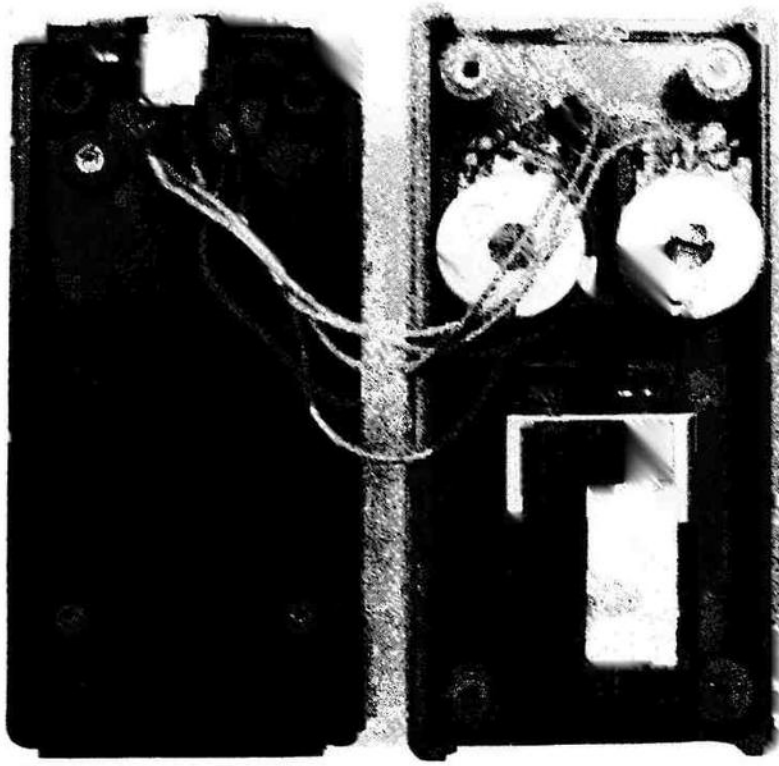
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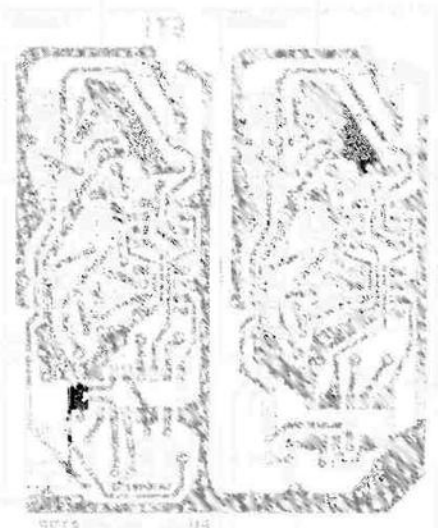


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# PROJECT 1 Robot Motor Control Part 2



The purpose of this project is to design and build a motor control system for a robot. The system will be used to control the movement of a robot in a controlled environment. The robot will be equipped with two DC motors, one for forward motion and one for reverse motion. The control system will be implemented using a microcontroller and a motor driver. The microcontroller will receive input from a user and send control signals to the motor driver. The motor driver will then provide the appropriate current to the motors to move the robot in the desired direction. The system will be tested by programming the microcontroller to move the robot in a square pattern.



The motor driver is a key component in the system. It is responsible for providing the correct current and voltage to the motors. The driver consists of two transistors, one for each motor. The microcontroller sends a pulse-width modulated (PWM) signal to the base of the transistors, which then switches the current to the motors. The motor driver also includes a diode to protect the transistors from back EMF generated by the motors.

The microcontroller is the brain of the system. It receives input from a user and sends control signals to the motor driver. The microcontroller is programmed to move the robot in a square pattern. It does this by sending a sequence of PWM signals to the motor driver, which then moves the robot in the desired direction for a set amount of time.

The system is tested by programming the microcontroller to move the robot in a square pattern. The robot is placed on a flat surface, and the microcontroller is programmed to move it in a square pattern. The system is tested by observing the robot's movement and adjusting the program as needed. The system is considered successful if the robot moves in a square pattern.

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